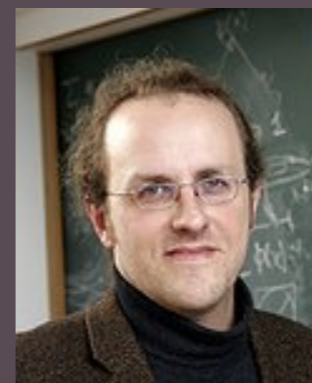


BaCaDI: Bayesian Causal Discovery with Unknown Interventions

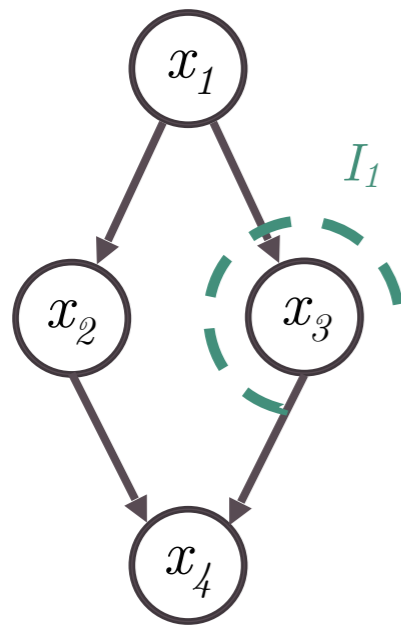
Alexander Hägele, Jonas Rothfuss, Lars Lorch, Vignesh Ram Somnath,
Bernhard Schölkopf, Andreas Krause



Toy example: Causal Bayesian Networks

- Factorized likelihood

$$p(x_1, \dots, x_4 \mid \mathbf{G}) = p(x_1) \cdot p(x_2 \mid x_1) \cdot p(x_3 \mid x_1) \cdot p(x_4 \mid x_2, x_3)$$



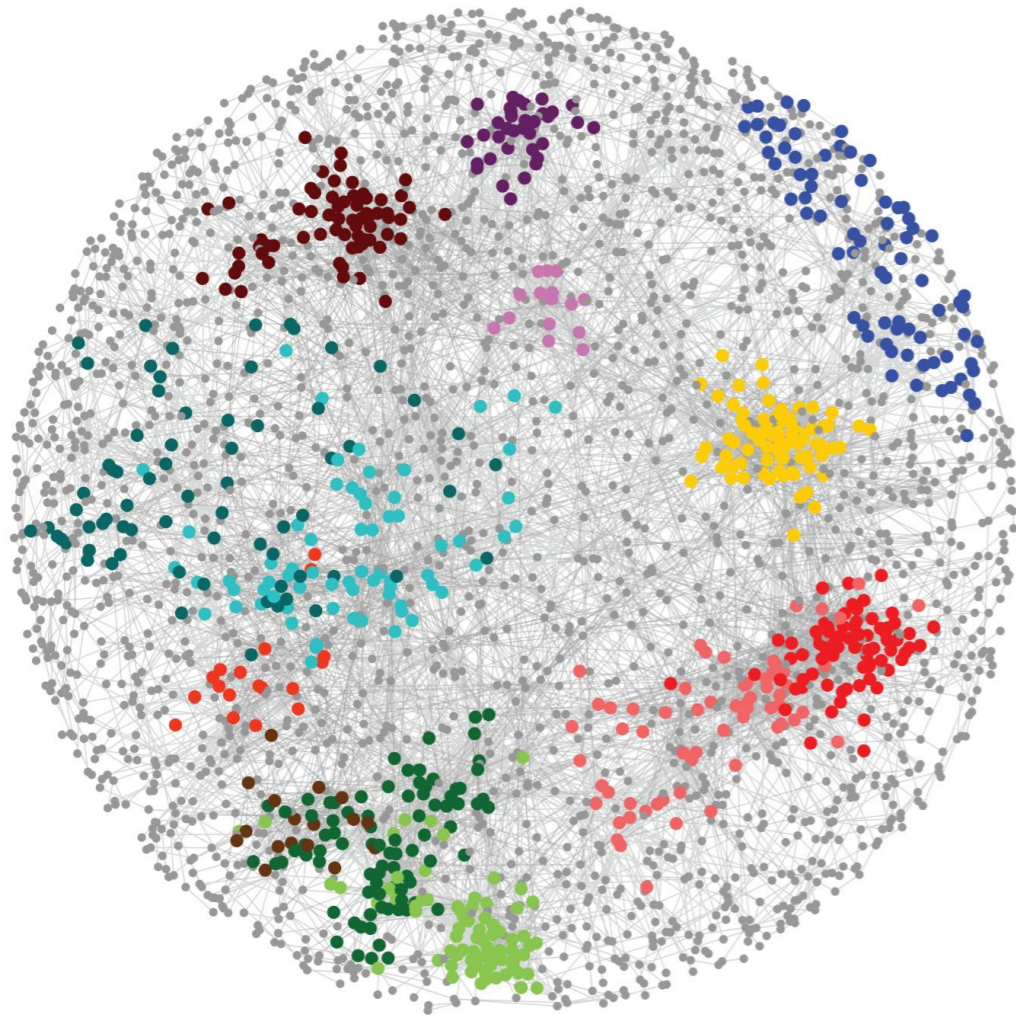
- ... with local switching after intervention

$$p(x_1, \dots, x_4 \mid \mathbf{G}, I_1) = p(x_1) \cdot p(x_2 \mid x_1) \cdot p^I(x_3) \cdot p(x_4 \mid x_2, x_3)$$

e.g. hard intervention

- Can try and learn graph from data — interventions help!
- ... but what if interventions (targets and/or distribution) are unknown?

Learning causal mechanisms from experimentation & interventions

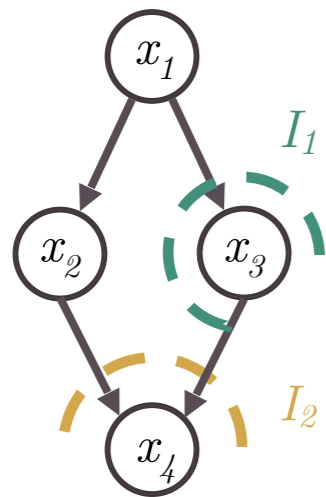


Global genetic landscape of the cell

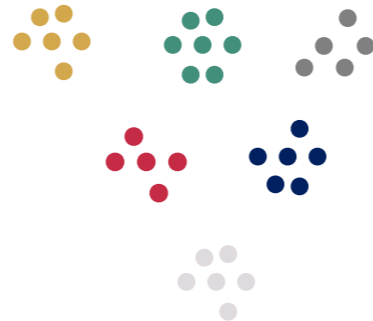
- Collect datasets from *same* underlying causal system under multiple interventions
- Biology: single-cell expression with interventions (drug candidates, gene knockouts)
- *Costly interventions & uncertain (off-target effects, ...)*

Causal Discovery from multiple contexts

Observe samples from same underlying causal graph (DAG) across different contexts



Dataset



Context	x_1	x_2	x_3	x_4
●	-1.45	0.89	1.01	0.40
●	-1.21	0.68	0.98	0.36
●	-1.34	0.84	-1.24	-2.22
...

$$\mathbf{D} = \{\mathcal{D}_1, \dots, \mathcal{D}_M\}$$

$$\mathcal{D}_k = \{\mathbf{x}^{(k,1)}, \dots, \mathbf{x}^{(k,n_k)}\}$$

with corresponding unknown interventions

$$\mathcal{I} = \{I_1, \dots, I_M\}$$

Goal: learn $\mathbf{G}, \Theta, \mathcal{I}$ and rigorously account for *uncertainty*

Bayesian Causal Discovery from multiple contexts

- Bayesian Inference of CBNs:

$$p(\mathbf{G}, \Theta \mid \mathcal{D}) \underset{\text{posterior}}{\propto} \underset{\text{prior terms}}{p(\mathbf{G})p(\Theta \mid \mathbf{G})} \underset{\text{likelihood}}{p(\mathcal{D} \mid \mathbf{G}, \Theta)} \longrightarrow \mathbb{E}_{p(\mathbf{G}, \Theta \mid \mathcal{D})} [f(\mathbf{G}, \Theta)]$$

- Known interventions?

insert \mathcal{I}

- Unknown interventions?

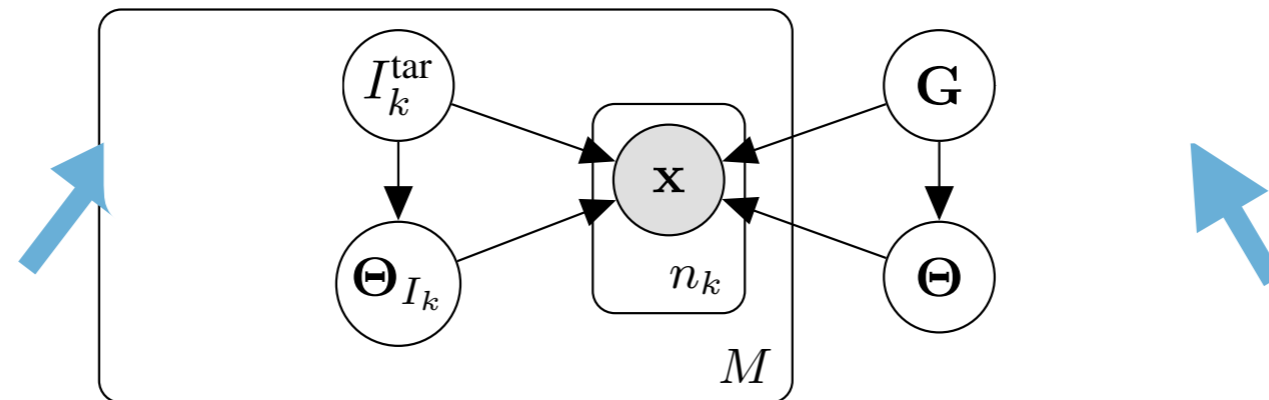
$$p(\mathbf{G}, \Theta, \mathcal{I} \mid \mathbf{D}) \underset{\text{posterior}}{\propto} \underset{\text{graph prior}}{p(\mathbf{G})p(\Theta \mid \mathbf{G})} \prod_{k=1}^M \underset{\text{interv. prior}}{p(I_k^{\text{tar}})} \underset{\text{interv. likelihood}}{p(\Theta_{I_k} \mid I_k^{\text{tar}})p(\mathcal{D}_k \mid \mathbf{G}, \Theta, I_k)}$$

- Intractable!

BaCaDI: A Differentiable Generative Model over CBNs and Interventions

Without loss of generality, use latent variables

$$p(\mathbf{G}, \Theta, \mathcal{I} \mid \mathbf{D}) \longrightarrow p(\underline{\mathbf{Z}}, \Theta, \underline{\Gamma}, \Theta_I \mid \mathbf{D})$$



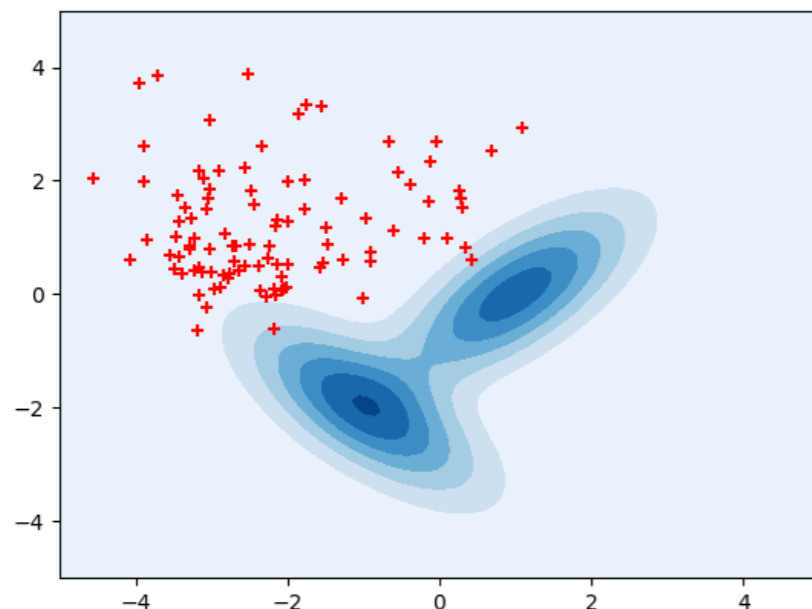
[DiBS, Lorch et al. 2021]

Joint Variational Inference using SVGD



Implementation:

Use score and apply
particle transform **SVG**D



- *Note: joint inference*

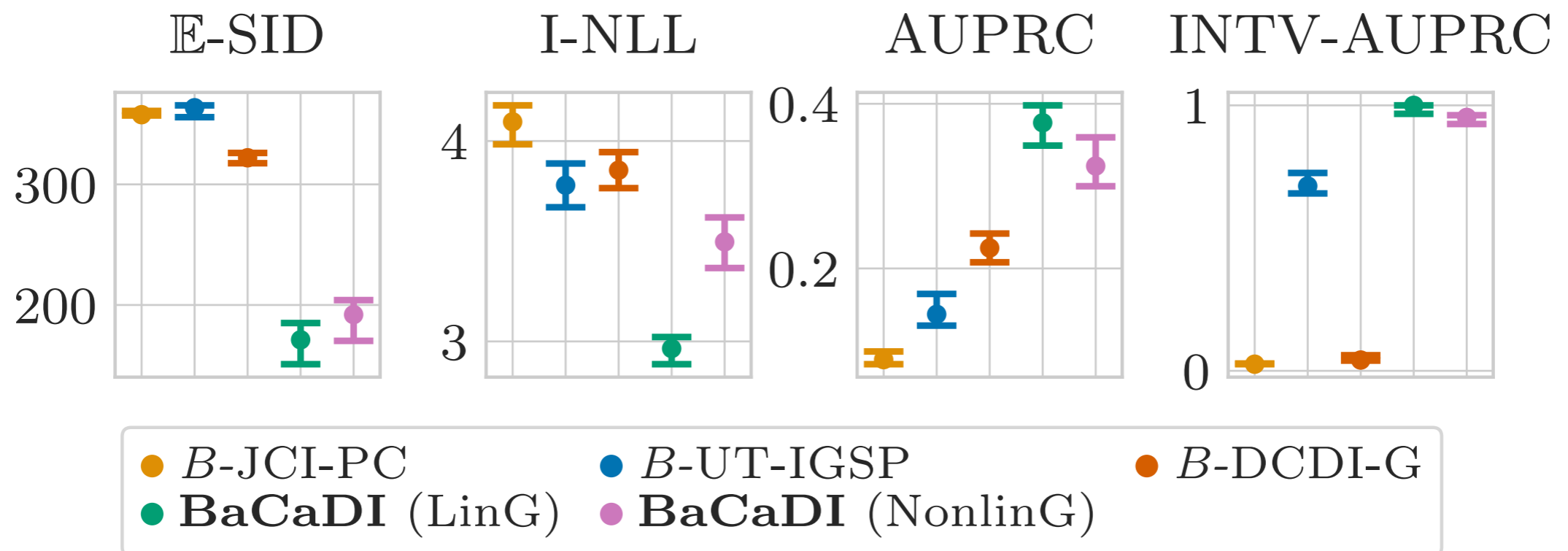
- Inference of the interventions and causal Bayesian network is interdependent
- Estimate epistemic uncertainty jointly

[Liu and Wang 2016]

Experiments: SERGIO

SERGIO: a single-cell expression simulator guided by gene regulatory networks

Interventions: gene knockouts



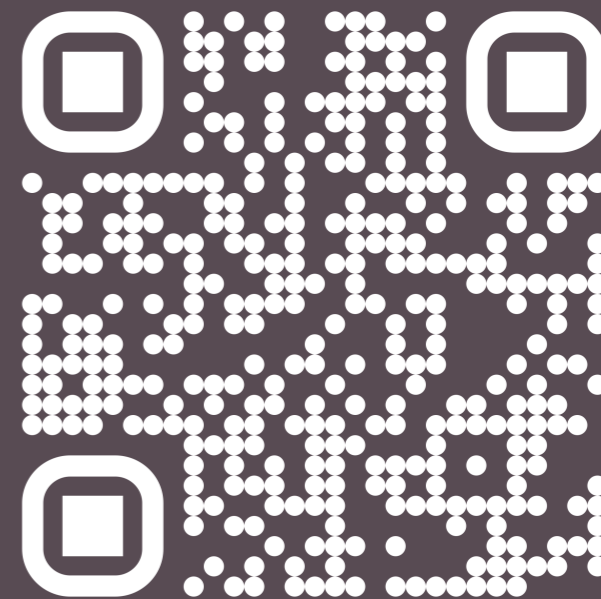
[Dibaeinia and Sinha 2020]

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Thank you!

- Paper: <https://arxiv.org/pdf/2206.01665.pdf>
- Contact: ahaegele@ethz.ch
- Code: <https://github.com/haeggee/bacadi>



BaCaDI: Bayesian Causal Discovery with Unknown Interventions

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Appendix

BaCaDI: Bayesian Causal Discovery with Unknown Interventions

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Experimental setup

- Sample random graphs (ER-2, SF-2) with 20 nodes and random parameters for local conditionals
- Random (hard) interventions on one target, bounded away from 0 with small noise
- 100 observational samples, 10 samples per interventional context
- Baselines — bootstrapped versions of:
 - JCI-PC [Mooij et al. 2016]
 - UT-IGSP [Squires et al. 2020]
 - DCDI-G [Brouillard et al. 2020]
- Metrics: Expected SID [Peters et al. 2015], held-out interventional NLL, AUPRC for edge prediction, AUPRC for intervention targets

Proposition 1

Proposition 1 *Under the extended generative model in Eq. 5 and Figure 1, it holds that*

$$\mathbb{E}_{p(\mathbf{G}, \Theta, \mathcal{I} | \mathbf{D})} [f(\mathbf{G}, \Theta, \mathcal{I})] = \tag{6}$$
$$\mathbb{E}_{p(\mathbf{Z}, \Theta, \Gamma, \Theta_{\mathcal{I}} | \mathbf{D})} \left[\frac{\mathbb{E}_{p(\mathbf{G} | \mathbf{Z})} \mathbb{E}_{p(\mathcal{I}^{\text{tar}} | \Gamma)} [f(\mathbf{G}, \Theta, \mathcal{I}) \cdot \Psi]}{\mathbb{E}_{p(\mathbf{G} | \mathbf{Z})} \mathbb{E}_{p(\mathcal{I}^{\text{tar}} | \Gamma)} [\Psi]} \right]$$

with weighting $\Psi = p(\Theta | \mathbf{G})p(\Theta_{\mathcal{I}} | \mathcal{I}^{\text{tar}})p(\mathbf{D} | \mathbf{G}, \mathcal{I}, \Theta)$ and $p(\mathbf{D} | \mathbf{G}, \mathcal{I}, \Theta) = \prod_{k=1}^M p(\mathcal{D}_k | \mathbf{G}, \Theta, I_k^{\text{tar}}, \Theta_{I_k})$.

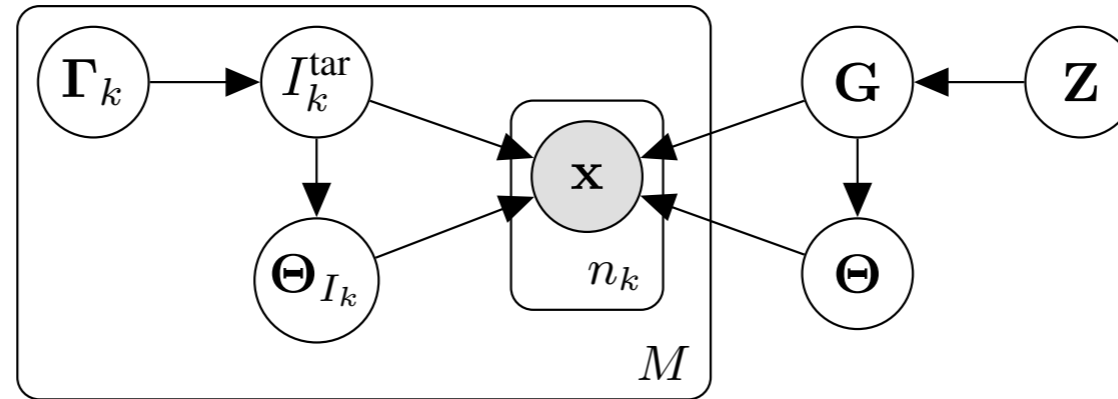
Proposition 2

Proposition 2 *As $\alpha \rightarrow \infty$ and $\beta \rightarrow \infty$ the posterior expectation in Prop. 1 converges to the simpler expression*

$$\begin{aligned} & \mathbb{E}_{p(\mathbf{G}, \Theta, \mathcal{I}^{\text{tar}}, \Theta_{\mathcal{I}} | \mathbf{D})} [f(\mathbf{G}, \Theta, \mathcal{I}^{\text{tar}}, \Theta_{\mathcal{I}})] \\ & \rightarrow \mathbb{E}_{p(\mathbf{Z}, \Theta, \Gamma, \Theta_{\mathcal{I}} | \mathbf{D})} [f(\mathbf{G}_{\infty}(\mathbf{Z}), \Theta, \mathcal{I}_{\infty}^{\text{tar}}(\Gamma), \Theta_{\mathcal{I}})] \end{aligned} \quad (13)$$

with $\mathbf{G}_{\infty}(\mathbf{Z})_{i,j} = \mathbf{1}_{\mathbf{u}_i^{\top} \mathbf{v}_j > 0}$ and $\mathcal{I}_{\infty}^{\text{tar}}(\Gamma)_{k,i} = \mathbf{1}_{\gamma_{i,k} > 0}$. In the limit, the marginal posterior over discrete structures $p(\mathbf{G}, \mathcal{I}^{\text{tar}} | \mathbf{D})$ is supported on $\{\mathbf{G} | \mathbf{G} \in \{0, 1\}^{d \times d} \wedge \mathbf{G} \text{ is acyclic}\} \times \{0, 1\}^{M \times d}$ and, thus, a valid probability mass function over DAGs and intervention targets.

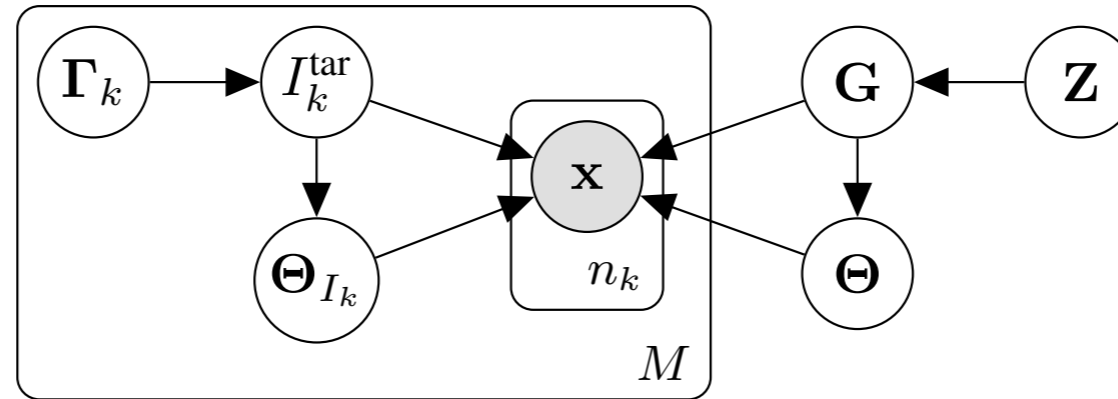
Full factorization



$$p(\mathbf{Z}, \mathbf{G}, \Theta, \Gamma, \mathcal{I}, \mathbf{D}) = \underbrace{p(\mathbf{Z})p(\mathbf{G}|\mathbf{Z})p(\Theta|\mathbf{G})}_{\text{generative process CBN}} \quad (5)$$

$$\cdot \prod_{k=1}^M \underbrace{p(\Gamma_k)p(I_k^{\text{tar}}|\Gamma_k)p(\Theta_{I_k}|I_k^{\text{tar}})}_{\text{generative process intervention}} \underbrace{p(\mathcal{D}_k|\mathbf{G}, \Theta, I_k^{\text{tar}}, \Theta_{I_k})}_{\text{interventional likelihood}}$$

Generative model of graph

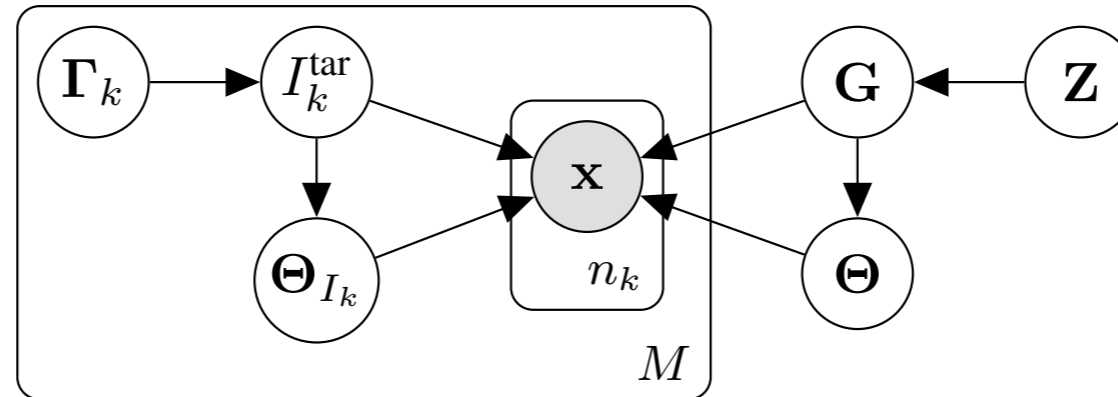


$$p_\alpha(\mathbf{G}|\mathbf{Z}) = \prod_{i=1}^d \prod_{j \neq i}^d p_\alpha(g_{ij}|\mathbf{u}_i, \mathbf{v}_j) \quad (7)$$

with $g_{ij}|\mathbf{u}_i, \mathbf{v}_j \sim \text{Bern}(\sigma_\alpha(\mathbf{u}_i^\top \mathbf{v}_j))$

$$p_\beta(\mathbf{Z}) = p(\mathbf{U}, \mathbf{V}) \propto \underbrace{\exp(-\beta \mathbb{E}_{p(\mathbf{G}|\mathbf{Z})}[h(\mathbf{G})])}_{\text{acyclicity prior}} \cdot \underbrace{\prod_{i=1}^d \mathcal{N}(\mathbf{u}_i|\mathbf{0}, \eta_Z^2 \mathbf{I}) \mathcal{N}(\mathbf{v}_i|\mathbf{0}, \eta_Z^2 \mathbf{I})}_{\text{inference stability}} \quad (8)$$

Generative model of interventions



$$p(\mathcal{I}^{\text{tar}} | \Gamma) = \prod_{k=1}^M \prod_{i=1}^d p_{\alpha}(I_{k,i}^{\text{tar}} | \gamma_{k,i}) \quad (9)$$

with $I_{k,i}^{\text{tar}} | \gamma_{k,i} \sim \text{Bern}(\sigma_{\alpha}(\gamma_{k,i}))$

$$p(\Gamma) \propto \prod_{k=1}^M \underbrace{\exp(-\lambda \|\sigma_{\alpha}(\Gamma_k)\|_1)}_{\text{sparse masks}} \cdot \prod_{i=1}^d \underbrace{\text{Beta}(\sigma_{\alpha}(\gamma_{k,i}); \zeta_1, \zeta_2)}_{\text{sharp masks}} \underbrace{\mathcal{N}(\gamma_k | \mathbf{0}, \eta_{\gamma}^2 \mathbf{I})}_{\text{inference stability}} \quad (10)$$

Log posterior score

$$\begin{aligned} & \nabla_{\Gamma} \log p(\mathbf{Z}, \Theta, \Gamma, \Theta_{\mathcal{I}} | \mathbf{D}) \\ &= \nabla_{\Gamma} \log p(\Gamma) + \frac{\nabla_{\Gamma} \mathbb{E}_{p(\mathbf{G} | \mathbf{Z})} \mathbb{E}_{p(\mathcal{I}^{\text{tar}} | \Gamma)} [\Psi]}{\mathbb{E}_{p(\mathbf{G} | \mathbf{Z})} \mathbb{E}_{p(\mathcal{I}^{\text{tar}} | \Gamma)} [\Psi]} \end{aligned}$$

with weighting $\Psi = p(\Theta | \mathbf{G}) p(\Theta_{\mathcal{I}} | \mathcal{I}^{\text{tar}}) p(\mathbf{D} | \mathbf{G}, \mathcal{I}, \Theta)$ and $p(\mathbf{D} | \mathbf{G}, \mathcal{I}, \Theta) = \prod_{k=1}^M p(\mathcal{D}_k | \mathbf{G}, \Theta, I_k^{\text{tar}}, \Theta_{I_k})$.